51

Nested Sampling

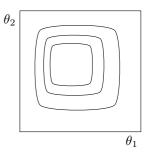


Figure 51.1. Contour plot of a likelihood function $\mathcal{L}(\boldsymbol{\theta})$.

Figures by David MacKay.

John Skilling's way of thinking about the integral $Z = \int\! d^K {m heta} \,\, {\cal L}({m heta}) \pi({m heta})$

Let x(L) be the prior mass enclosed within the contour $\mathcal{L}(\boldsymbol{\theta}) = L$, and L(x) be the contour value such that the volume enclosed is x.

$$Z = \int dx \ L(x).$$

$$\theta_2$$

$$\theta_1$$

$$L(x)$$

$$\theta_1$$

$$\theta_1$$

$$\theta_2$$

$$\theta_1$$

$$\theta_2$$

$$\theta_1$$

$$\theta_2$$

$$\theta_1$$

$$\theta_1$$

$$\theta_2$$

$$\theta_2$$

$$\theta_1$$

$$\theta_2$$

$$\theta_2$$

$$\theta_3$$

$$\theta_4$$

$$\theta_1$$

$$\theta_2$$

$$\theta_3$$

$$\theta_4$$

$$\theta_4$$

$$\theta_4$$

$$\theta_4$$

$$\theta_5$$

$$\theta_6$$

$$\theta_7$$

$$\theta_8$$

$$\theta_$$

An example of L(x)

Let θ be a collection of G unknown binary variables $\theta_g \in \{0, 1\}$, and let our data be a list of G independent noisy observations of them – one observation each. So the likelihood function will have the form

$$\mathcal{L}(\boldsymbol{\theta}) \propto \exp\left(\sum_{g=1}^{G} b_g \theta_g\right),$$
 (51.1)

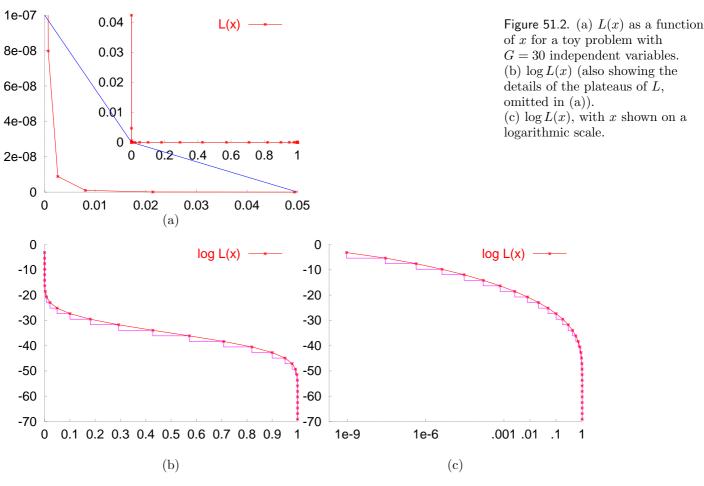
where the b_g is the bias for θ_g towards or away from 1 (if b_g is positive or negative respectively). If all the noisy observations have the same noise level then the magnitudes of the b_g will be the same for all g.

Clearly the posterior distribution is separable. This is a very simple inference problem, but it epitomizes some of the issues arising in more realistic problems.

To connect to my chapter on sex, we can note that if all the b_g happen to be +b then the log-likelihood is proportional to the fitness $F \equiv \sum_{g=1}^{G} \theta_g$ that I assumed there.

So, what does L(x) look like? The volume fraction $x = 1/2^G$, is associated with the unique maximum likelihood state. Moving away from that corner of the hypercube, the log-likelihood increases in proportion to the Hamming distance from that corner, and the number of states at Hamming distance d is $\binom{G}{d}$. Or, in terms of the fitness F, which is G - d, the number of states is $\binom{G}{F}$.

Figure 51.2 shows L(x) from various points of view, for the case where the number of independent variables is G=30. Of these graphs, 51.2(b) is perhaps the easiest to relate to: flipping the two axes round, this graph is almost exactly the cumulative normal distribution function, shifted and scaled.

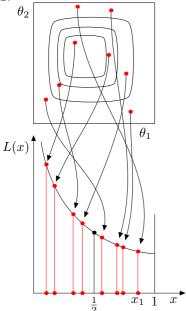


Notice that L(x) is a very sharply increasing function as $x \to 0$. $\log L(x)$ is locally a roughly linear function of $\log x$ (if we neglect the plateaus of L, so locally we can think of L as behaving like a power law $L(x) \simeq x^{-p}$, for some p. For this example, a crude but useful description of the situation is that halving the volume x increases $\log L(x)$ by a constant of order 1.

Nested sampling

We start by drawing N points uniformly from the prior. Let N=8, say. Roughly half of the points fall inside the shaded region corresponding to the contour with x=1/2. Roughly one quarter of them are inside the contour associated with x=1/4. Roughly one eighth of them are inside the contour associated with x=1/8.

We can associate each point θ_i with an x-value, namely the volume that would be enclosed by the contour $\mathcal{L}(\theta_i)$. Since the points are uniformly distributed under the prior, the N x-values are uniformly distributed between 0 and 1.



Let x_1 be the largest x-value. The typical value of x_1 is something like N/(N+1) or $e^{-1/N}$. (The former is its arithmetic expected value, the latter its geometric mean.) We introduce a contour associated with this point.

Nested sampling now draws a new point, uniformly distributed in the region satisfying $\mathcal{L} \geq L(x_1)$. (We assume that this operation can be done, perhaps by a Markov chain method, just as annealing methods assume that a point can be drawn from the distribution $\propto \mathcal{L}^{\beta}$.) The new point is shown by the big purple dot.

We insert this new point and find among the N live points the biggest x-value, x_2 . (Remember there's a chance of roughly 1/N that the new point might have landed between the second-biggest x and x_1 .)

These x-values are uniformly distributed between 0 and x_1 .

We don't know the values of the volumes x_i , but we do know their order, since we know the values of $L(x_i) = \mathcal{L}(\theta_i)$.

At each iteration, the volume shrinks roughly by a factor of $e^{-1/N}$.

▶ 51.1 What is a typical sequence $\{x_i\}$ like?

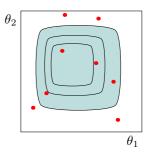


Figure 51.3. N = 8 points drawn uniformly from the prior.

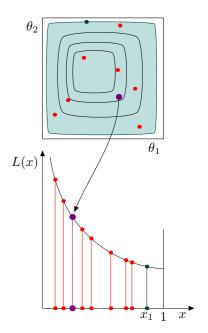


Figure 51.4. Replace the point at x_1 by a new point uniformly distributed between 0 and x_1 .

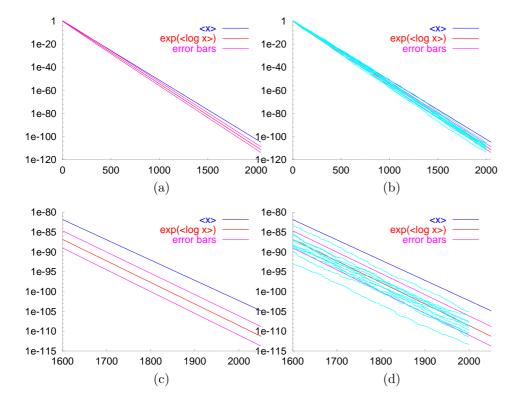


Figure 51.5. (a) The arithmetic and geometric means of x_i for the case N=8; also, error bars on the geometric mean,

$$\exp(-i/N \pm \sqrt{i}/N).$$

(b) A dozen samples from the distribution of $\{x_i\}$, for runs of duration 2000 steps.

(c,d) Detail of (a,b).