Teething problems! — Monte Carlo evaluation of Normalizing Constants

David J.C. MacKay Cavendish Laboratory mackay@mrao.cam.ac.uk

November 29, 1994— Draft 1.3

Abstract

This is a case study of the use of Monte Carlo methods to evaluate normalizing constants. I describe the trials and tribulations of importance sampling and of variational free energy approaches. The results are for a small model with just one latent variable.

More efficient evaluation of the evidence using importance sampling

If we create a sampling distribution $Q_j(\mathbf{x})$ that is similar to the posterior distribution $P(\mathbf{x}|\mathbf{F}_j)$ then the evidence integral can be approximated in terms of $\{\mathbf{x}^{(r)}\}_{r=1}^R$, which are random samples from $Q(\mathbf{x})$.:

$$L_{j}(\mathbf{w}) = \log \int d^{H}\mathbf{x} \, \exp(G_{j}(\mathbf{x}; \mathbf{w})) P(\mathbf{x})$$

$$\simeq \log \left[\frac{1}{R} \sum_{r} \exp(G_{j}(\mathbf{x}; \mathbf{w})) \frac{P(\mathbf{x})}{Q(\mathbf{x})} \right]$$

Later, I use this expression to evaluate accurately the evidence for a model that has been adapted by the simple Monte Carlo method above. The sampling distribution $Q_j(\mathbf{x})$ is set to a Gaussian with mean $\bar{\mathbf{x}}_j$ and diagonal covariance matrix Σ_j obtained from statistics returned by the simple algorithm.

The simple Monte Carlo algorithm gave the results illustrated in figure 4, as H and R were varied. The graphs show the evidence as a function of R. Notice that for R greater than 10 or so, the evidence value settles down, and increasing R makes negligible difference.

In the case of data TOY 1, as H is increased beyond 1, the evidence does not become either substantially larger or substantially smaller, even when the hidden vector has a dimensionality bigger than the dimensionality of the output space. This means that the model is finding a density of effective dimensionality about 1. There is apparently no overfitting problem.

	TOY 1														TOY 2
		i	1	2	3	4	5		i	1	2	3	4	5	
Data	j							j							
	1		5	2	0	0	0	1		5	2	0	0	1	_
	2		2	3	1	0	0	2		2	3	1	0	0	
	3		0	5	3	0	0	3		0	5	3	0	0	
	4		0	1	2	4	1	4		0	1	2	4	1	
	5		0	0	1	3	4	5		0	0	1	3	4	
	6		1	1	1	1	1	6		2	0	0	2	3	

Table 1: Parameters of models for the TOY problems

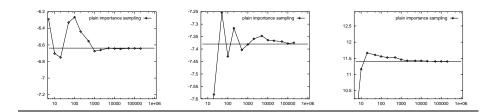


Figure 1: Toy example. Individual evidences (cols 1 and 2), and sum for all 6 data (col 3). Log evidence (y axis) is shown as a function of R (number of Monte Carlo samples, x axis). Top line = plain importance sampling results.

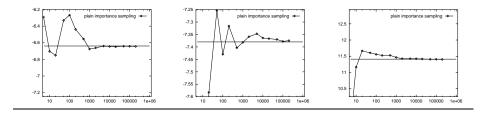


Figure 2: Toy example. CAUCHY importance sampler. Individual evidences (cols 1 and 2), and sum for all 6 data (col 3).

Log evidence (y axis) is shown as a function of R (number of Monte Carlo samples, x axis). Top line = plain importance sampling results.

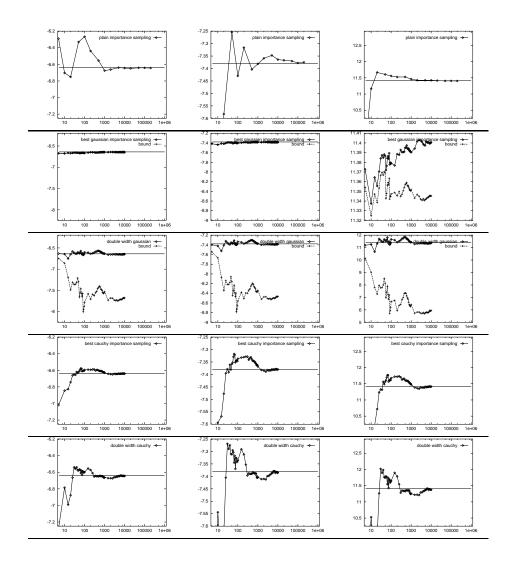
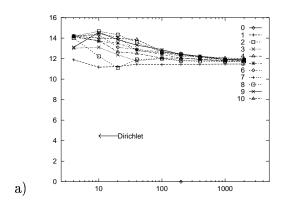


Figure 3: Toy example. Various samplers, well optimized. Individual evidences (cols 1 and 2), and sum for all 6 data (col 3).

Top line: plain importance sampling results. 2: Optimized gaussian. 3: Gaussian of double width. 4: Cauchy. 5: Cauchy of double width.



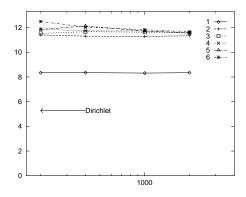


Figure 4: Toy examples. Estimated evidence.

b)

Log evidence (y axis) is shown as a function of R (number of Monte Carlo samples, x axis), for models with different numbers of hidden components (H between 0 to 7).

The evidence for the optimized Dirichlet model is also marked. All values are log evidences relative to the null model \mathcal{H}_0 .

a) Toy example number 1. b) Toy example number 2.

In the case of data TOY 2, the results are similar, except that the model with a two-dimensional componential representation is significantly more probable than the one-dimensional density network.

One way to understand what a model is doing is to look at its parameters (at least for small H). Table 1 shows the parameters for the nets with H=1 and H=2, ordered from i=1 to 5 vertically (c.f. horizontal in the data table earlier). Notice that the weights from the inputs in the TOY 1 cases capture the one dimension apparent to the human eye. When there are two inputs, the weight vectors for those inputs are not orthogonal; they are virtually identical (except for a change of sign). This similarity of the vectors of weights from the two inputs produces a low effective dimensionality in the output space.

When it is adapted to the TOY 2 data set, the parameters of the density network with two hidden components are very different. The two vectors over i are here virtually orthogonal, so that a fully two-dimensional distribution is produced in the output space.

Amino acid probabilities in aligned protein families

Figure 5 shows the estimated evidence, for J=60 examples, each with a count of $F_j \simeq 177$. Clearly many Monte Carlo samples are needed for a convergent estimate of the evidence.

The evidence for the Dirichlet model is also displayed. According to these results, a componential model with 13 components is more probable than the Dirichlet model.

(c) David MacKay

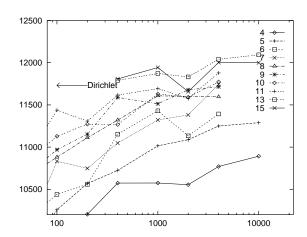


Figure 5: Amino acid modelling.

Estimated evidence, as a function of R (number of Monte Carlo samples, x axis), for models with different numbers of hidden components (H = 3 to 15).

The evidence for the optimized Dirichlet model is also marked. The evidence for other traditional Dirichlet models can also be reported: $\log P(D|\mathbf{u}=(1,1,\ldots,1))=10894.5;\ \log P(D|\mathbf{u}=(.05,.05,\ldots,.05))=11356.7.$

All values are log evidences relative to the null model \mathcal{H}_0 .